

Networks in Space

Spillovers in Amazon Deforestation

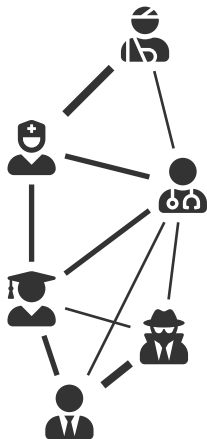
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Motivation

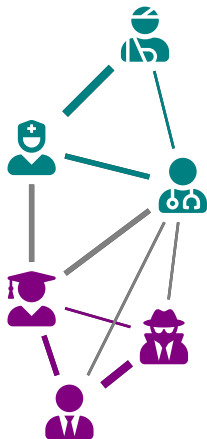
- *Economic agents* are **embedded in networks** that give rise to **spillover effects**, but
 - *we do not observe* underlying networks.

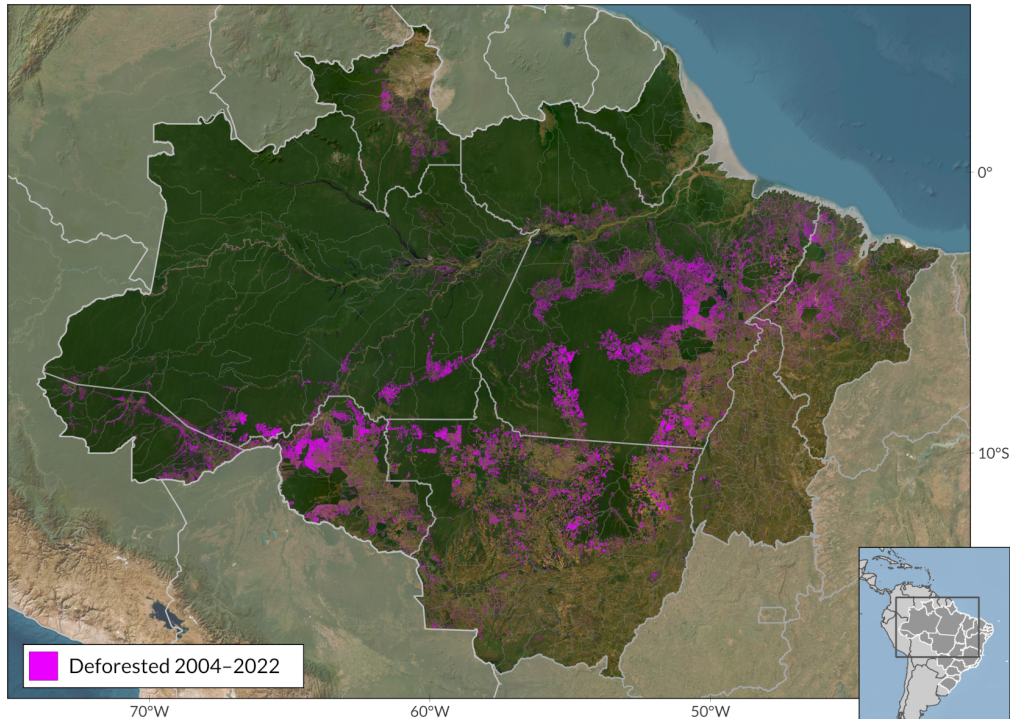


Motivation

- *Economic agents* are **embedded in networks** that give rise to **spillover effects**, but
 - we *do not observe* underlying networks.
- **Amazon deforestation**^a is coined by spillovers.
 - threatening the *climate*, biodiversity, ...

^aAnd countless other and related issues; see Alfaro-Ureña et al., [2022](#); Assunção and Rocha, [2019](#); Canen et al., [2023](#); Dhyne et al., [2021](#); Giovanni et al., [2022](#); Richards, [2017](#); Souza-Rodrigues, [2019](#); Vom Lehn and Winberry, [2022](#).





Research question

1. How can we **learn more about spillovers** using *available information*?
2. What is the *role of spillovers* in targeted **deforestation interventions**?

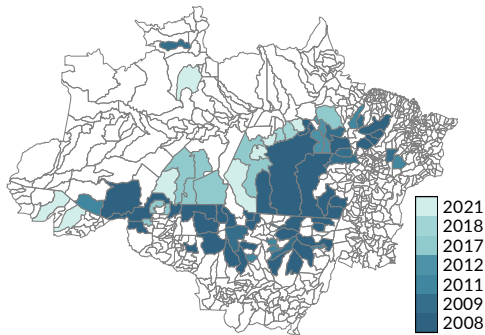


Figure 1: Priority municipalities in the *Brazilian Legal Amazon* and their date of designation.

Approach

- **Framework:** joint model of **spillovers & latent networks**
 - *deforestation model with peer effects*
 - *latent space network model*
- **Estimation:** flexible shrinkage for **data-driven insights**
 - *nuanced priors to use external information*
 - *full posterior inference via sampling*
- **Application:** deforestation in the **Brazilian Amazon**
 - *priority municipalities focus on hotspots*
 - *positive or negative spillovers, multiplier*

Findings

- **Joint model** — more accurate & deeper insights
- **Priority municipalities** — prevent deforestation
 - $\approx 65 \text{ km}^2$ prevented per year¹
 - *strategic complementarities* complicate inference

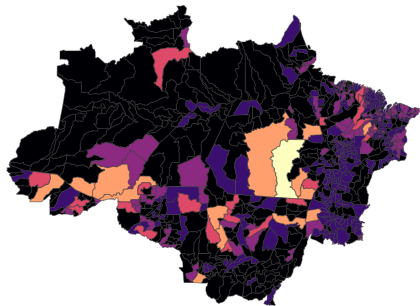


Figure 2: Relative strength of outward spillovers (out-degree centrality) as recovered from a flexible network model.

¹Compared to estimates of 20 without and 25 km² with contiguity spillovers.

Literature & Contributions

■ Deforestation — environmental economics²

- + *theoretical foundation* for deforestation spillovers
- + evidence for positive *spillovers to be utilized*, and *endogenous spillovers*

■ Spillovers — spatial & network econometrics³

- + *bridge* literatures via aggregation & latent space
- + *flexible* model that exploits available information

²Alix-Garcia and Gibbs, 2017; Amin et al., 2019; Araujo et al., 2023; Arima et al., 2014; Assunção and Rocha, 2019; Balboni et al., 2023; Burgess et al., 2023; Busch et al., 2015; Cisneros et al., 2015; de Andrade, 2016; Giljum et al., 2022; Gollnow et al., 2018; Harding et al., 2021; Kuschnig et al., 2023; Roitman et al., 2018; Richards, 2017; Salazar Restrepo and Leite Mariante, 2024; Souza-Rodrigues, 2019; Villoria et al., 2022.

³Auerbach, 2022; Battaglini et al., 2022; Boucher and Houndetoungan, 2023; Breza et al., 2020; Debarsy and LeSage, 2022; de Paula et al., 2023; Goldsmith-Pinkham and Imbens, 2013; Halleck Vega and Elhorst, 2015; Han and Lee, 2016; Herstad, 2023; Krisztin and Piribauer, 2022; Lam and Souza, 2020; Lewbel et al., 2023; Manresa, 2016; McCormick and Zheng, 2015; Neumayer and Plümper, 2016; Zhang and Yu, 2018.

Background

Background — priority municipalities

- 86 municipalities **blacklisted as deforestation hotspots**⁴
 - *focused* monitoring & enforcement
 - *spearhead* for interventions & *signal*
- Intervention **revitalized in 2023** ▶ development over time

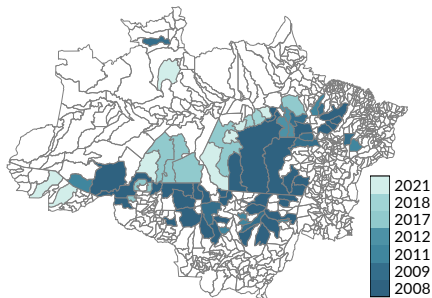


Figure 3: Priority municipalities and the date of designation (from 2008 until 2021).

⁴Studied by Arima et al., 2014; Assunção and Rocha, 2019; Cisneros et al., 2015; de Andrade, 2016.

Framework

Framework — setting

- Consider a **set of regions** $\mathcal{N}$, for which we observe random *responses* Y and *characteristics* X .



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- Regions have a **set of links** $\mathcal{E}$ between them — they are *connected in the network* $\mathcal{G} = \{\mathcal{N}, \mathcal{E}\}$.

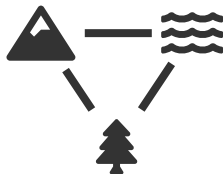


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- We want to **learn about the relationship**

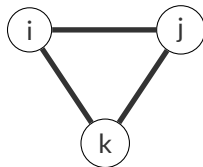
$$Y = f(X, \mathcal{G}) + \varepsilon,$$

- and will build a **hierarchical model** that *imposes structure* on both f and $\mathcal{G}$.



Framework — weighted digraph

Let $\mathcal{G}$ be a graph with a **set of nodes** $\mathcal{N}$ and *links* $\mathcal{E}$, which we allow to be ...

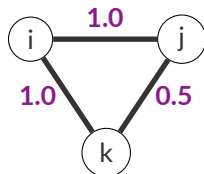


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- **weighted** — links are induced by

$$g : \mathcal{N} \times \mathcal{N} \mapsto \mathbb{R}^+,$$



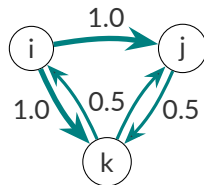
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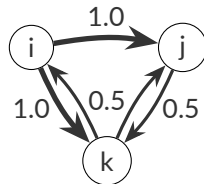
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Adjacency matrix

We represent $\mathcal{G}$ with the matrix $\mathbf{G}$, whose entries are $g_{ij} = g(i, j)$, or the **normalized adjacency matrix** $\mathbf{W}$.

$$\begin{bmatrix} 0 & g_{12} & \cdots & g_{1n} \\ g_{21} & 0 & \cdots & g_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ g_{n1} & g_{n2} & \cdots & 0 \end{bmatrix}$$

Framework — deforestation model

Individual i (in region n) chooses to exert effort $R_i \in \mathbb{R}$ to deforest their plots,^a **maximizing their utility**:

$$U_i(R_i | R_{-i}) = (X_i \tilde{\beta} + W_i X \tilde{\theta} + E_i) R_i + \tilde{\lambda} W_i R R_i - 0.5 R_i^2,$$

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The equilibrium best response is *observable*; we observe **regional aggregates** thereof $Y_n = \sum_{i \in n} R_i$. [► Details](#)

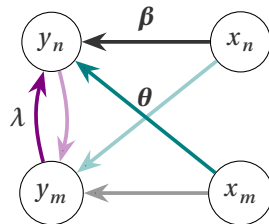
^aThat is, they allocate area between cleared land and forest.

Framework — empirical model

The empirical equivalent is the **linear network model**

$$\mathbf{y} = \lambda \mathbf{W} \mathbf{y} + \mathbf{W} \mathbf{X} \boldsymbol{\theta} + \mathbf{X} \boldsymbol{\beta} + \mathbf{e},$$

- with **global spillovers** (endogenous), and
- **local spillovers** (contextual) between nodes.



► Assumptions

Framework — empirical model

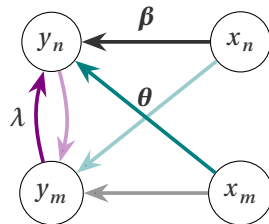
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Special cases

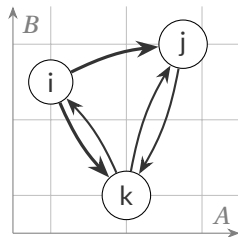
Special cases are the *linear-in-means* and *spatial Durbin* models, which **assume a specific $\mathbf{W}$ is known**.



► Assumptions

Framework — network model

- Assume that **nodes can be embedded** in a **latent space** $(\mathcal{P}, s)$.^a We have $g_{ij} = s(\Omega, P_i, P_j)$.



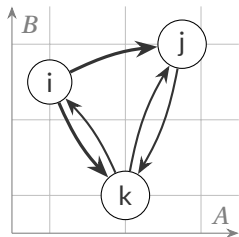
^aThis is natural in our spatial setting, and has been used successfully for modelling social networks (going back to Hoff et al., [2002](#)).

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- We can *model links* as decaying in a **metric** d ,

$$s := \exp \left\{ -\delta \times d(P_i, P_j) \right\} \quad \forall i \neq j,$$

- where $P_i \in \mathbb{R}^D$ denotes the (latent) *position* of i ,
- and the *parameters* control the **rate of decay**.



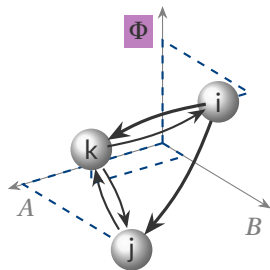
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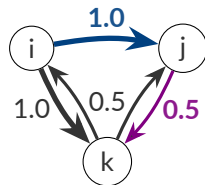
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In practice, we **normalize** the adjacency matrix to **W**, s.t. spillovers are identified.



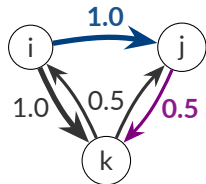
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Row normalization

The standard is to transform $\tilde{W}$ to be **row-stochastic**, such that $\sum_j w_{ij} = 1 \ \forall i$.



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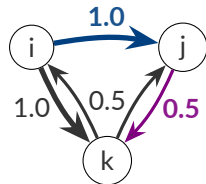
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Scalar normalization

We will use **scalar normalization**, such that $w_{ij} = g_{ij} \times \varsigma \ \forall i, j$, in order to **preserve the network structure**. ► Which scalar?



$$\mathbf{G} = \begin{bmatrix} 0 & 1.0 & 1.0 \\ 0 & 0 & 0.5 \\ 0.5 & 0.5 & 0 \end{bmatrix} = \mathbf{W},$$

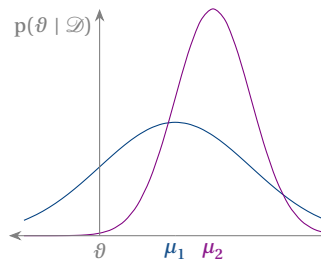
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Estimation

Estimation or: How I Learned to Stop Worrying and Love MCMC

I adopt a fully **Bayesian approach**, using *Markov chain Monte Carlo* (MCMC) to obtain posterior samples.

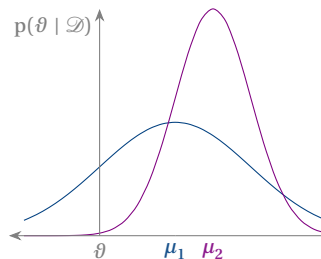
- + nuanced framework to *introduce information*
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- + *uncertainty* quantification
- *computational cost*
- put thought into *priors*



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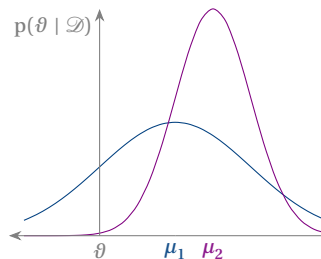
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Results

Results — deforestation

- Average effect of **blacklisting**
- Deforestation in 808 regions from 2004–2022

$$\mathbf{y}_t = \lambda \mathbf{W}(\cdot) \mathbf{y}_t + \mathbf{X}_t \boldsymbol{\beta} + \mathbf{W}(\cdot) \mathbf{X}_t \boldsymbol{\theta} + \boldsymbol{\mu} + \xi_t + \mathbf{e}_t$$

- Increasingly *flexible networks*
 - *known network* ($\mathbf{0}$, contiguity)
 - *latent space network model*

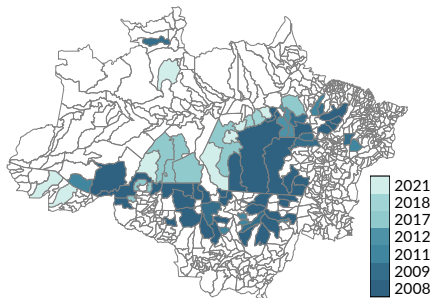
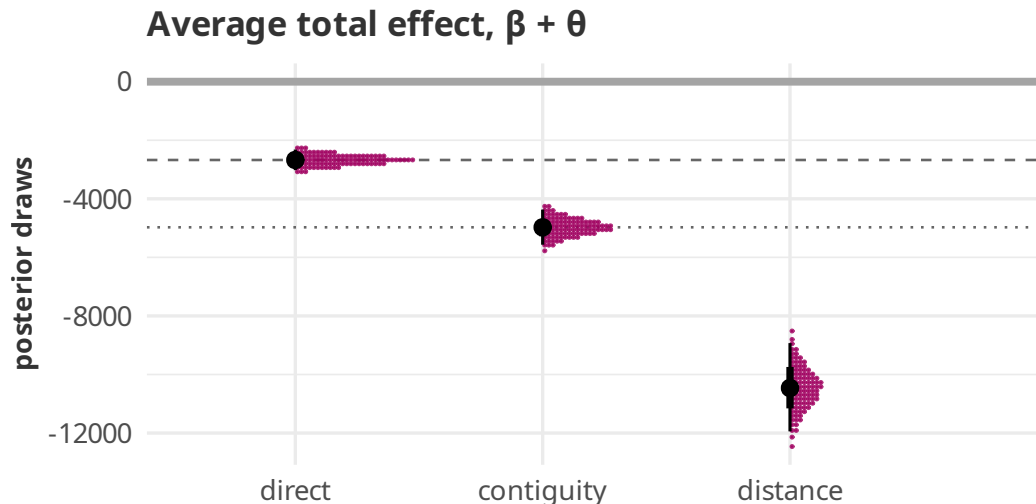


Figure 4: Priority municipalities and the date of designation (from 2008 until 2021).

Direct Effects and Local Spillovers

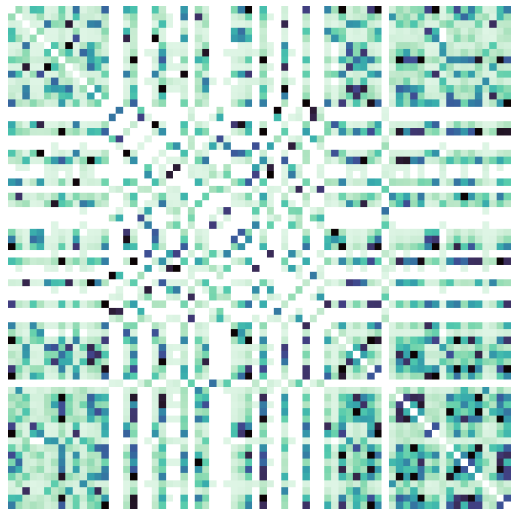
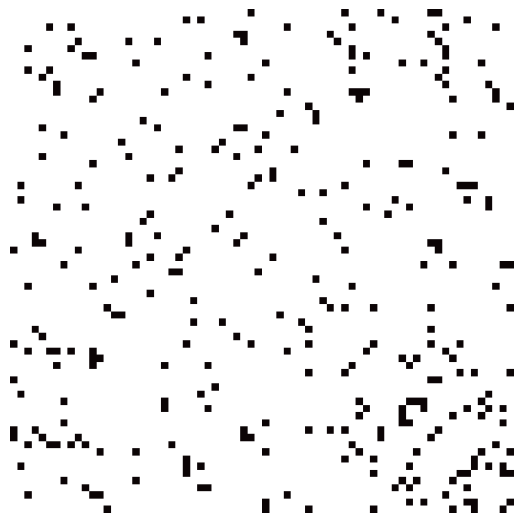
$$\mathbf{y}_t = \mathbf{X}_t \boldsymbol{\beta} + \mathbf{W}(\delta, \eta_t, \varphi_i) \mathbf{X}_t \boldsymbol{\theta} + \boldsymbol{\mu} + \boldsymbol{\xi}_t + \mathbf{e}_t$$

Results — direct effects & local spillovers

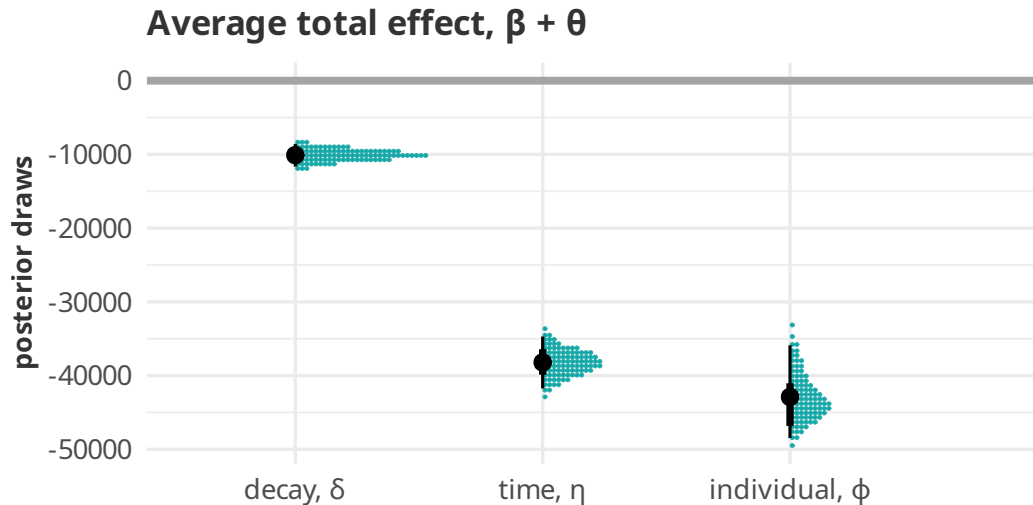


$$\mathbf{y}_t = \mathbf{X}_t\boldsymbol{\beta} + \mathbf{W}\mathbf{X}_t\boldsymbol{\theta} + \boldsymbol{\mu} + \boldsymbol{\xi}_t + \mathbf{e}_t$$

Results — contiguity and distance networks



Results — local spillovers with a network model [▶ All models](#)



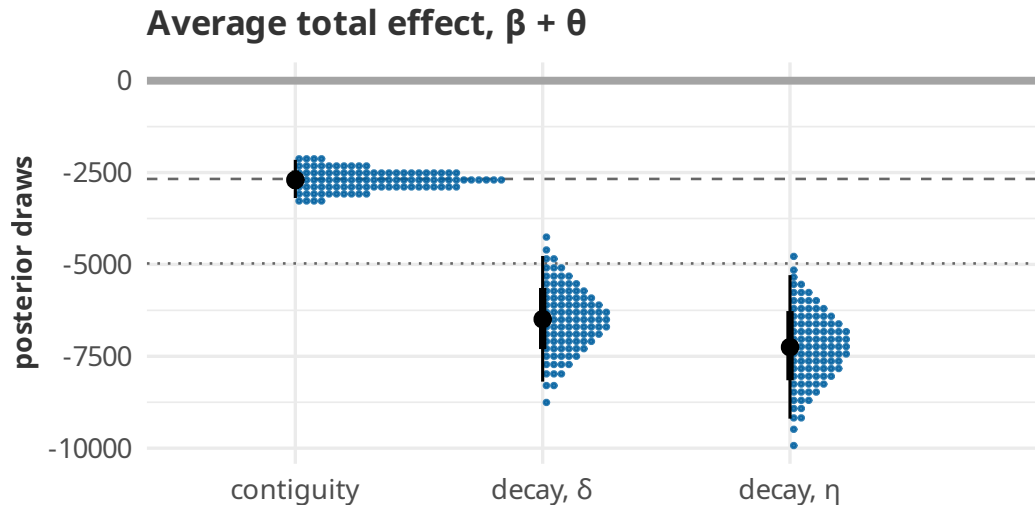
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Local and Global Spillovers

$$\mathbf{y}_t = \lambda \mathbf{W}(\delta, \eta_t) \mathbf{y}_t + \mathbf{X}_t \boldsymbol{\beta} + \mathbf{W}(\delta, \eta_t) \mathbf{X}_t \boldsymbol{\theta} + \boldsymbol{\mu} + \boldsymbol{\xi}_t + \mathbf{e}_t$$

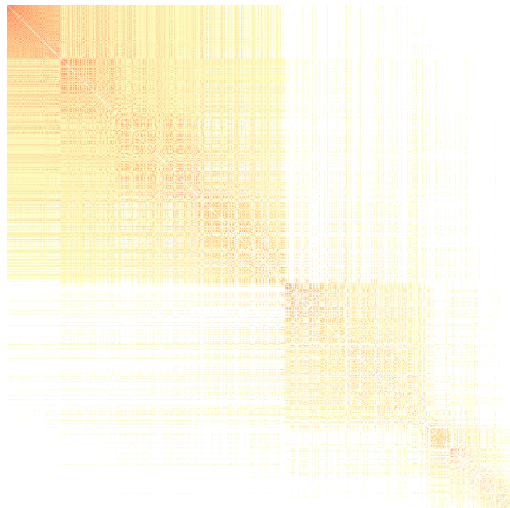
Results — local and global spillovers

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Results — distance and popularity networks



Results — recovering network centrality

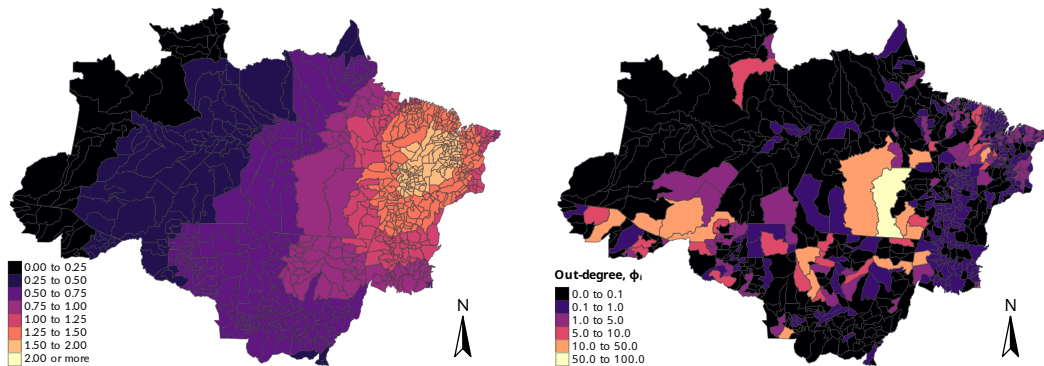


Figure 5: Mean out-degree centrality of $W(\delta)$ and $W(\delta, \phi_i)$. ► $W(\delta, P)$

Results — simulation

1. US states, **asymmetry** from population [▶ Results](#)
2. US states, **weak prior** position [▶ Results](#)
3. Erdős–Rényi graph, latent space **approximation** [▶ Results](#)

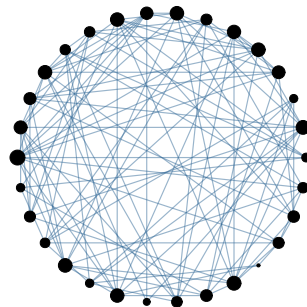
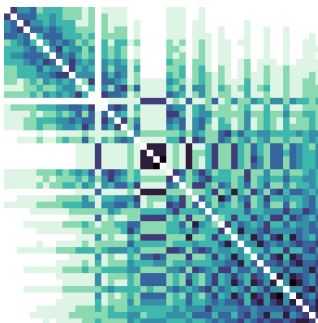
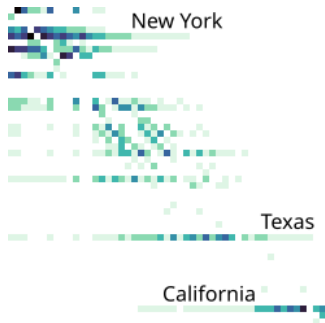


Figure 6: Illustration of the asymmetric network between US states, the centroid network, and the Erdős–Rényi graph.

Conclusion

Conclusion

- **Joint model** of *spillovers* and *networks*
 - leverages *data* and *structure*
 - yields *deeper insights* into spillovers
 - moderate to pronounced *computational costs*
- **Amazon deforestation** spillovers
 - *underestimated* with restrictive models
 - confounding from *endogenous spillovers*
 - *network structure* to utilize

Thank you for your attention!

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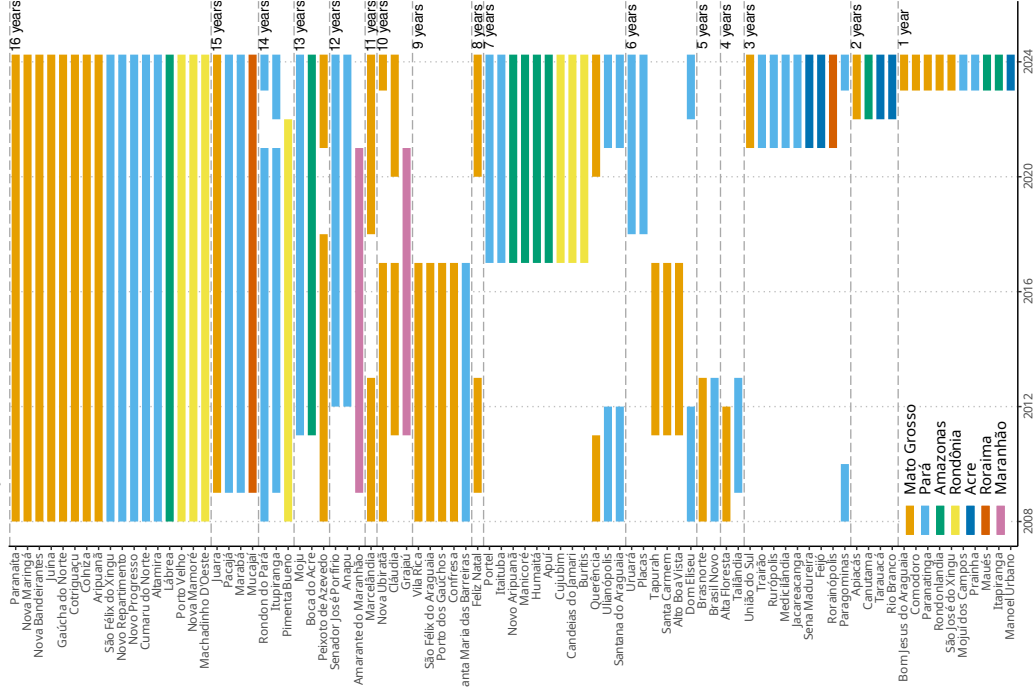
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Priority municipalities



Fine status (by value)

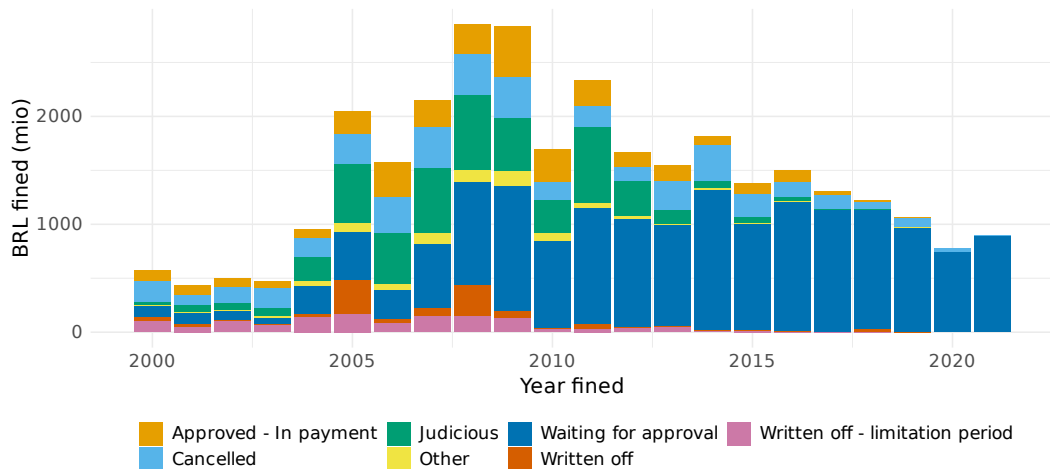


Figure 7: Status of forest-related environmental fines (Kuschnig et al., 2023).

Fine payments (by value)

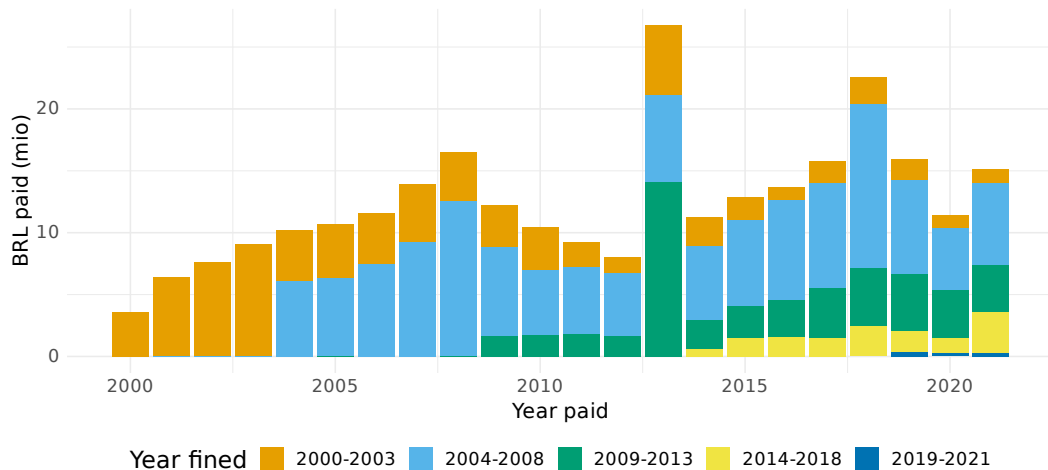


Figure 7: Status of forest-related environmental fines (Kuschnig et al., 2023).

The individual equilibrium best response is⁵

$$R_i = \tilde{\lambda} W_i R + X_i \tilde{\beta} + W_i X \tilde{\theta} + E_i$$

We observe **aggregates**; **region-internal** networks are absorbed:

$$\begin{bmatrix} R_{m1} \\ R_{m2} \\ R_{n1} \\ R_{n2} \\ R_{o1} \\ \vdots \end{bmatrix} = \tilde{\lambda} \begin{bmatrix} 0 & w_{m1m2} & w_{m1n1} & w_{m1n2} & \dots \\ w_{m2m1} & 0 & w_{m2n1} & w_{m2n2} & \dots \\ w_{n1m1} & w_{n1m2} & 0 & w_{n1n2} & \dots \\ w_{n2m1} & w_{n2m2} & w_{n2n1} & 0 & \dots \\ \vdots & \vdots & \vdots & \ddots & \vdots \end{bmatrix} R + \dots$$

⁵Subject to conditions (see Blume et al., 2015) including stationarity of the network.

For the network, we require (i) stationarity of the network filter $\mathbf{I} - \lambda \mathbf{W}$, (ii) spillover effects that do not cancel out $\lambda \beta + \theta \neq 0$, (iii) network asymmetry, i.e., $\text{diag}(\mathbf{W}^2) \propto \iota$ (see de Paula et al., 2023). If, additionally, $\lambda > 0$ the parameters are globally identified.

Due to the presence of the endogenous spillover and individual fixed effects, we require **strict exogeneity** to consistently estimate the parameters. (That is, there is no autocorrelation of Y and errors are uncorrelated with the network structure.)

The endogenous spillover gives rise to a multiplier effect, but is often suppressed due to the unloved assumptions required; if it is suppressed, however, other network effects may be confounded.

Normalization for interpretation

[◀ Back](#)

Consider a contextual model,

$$\mathbf{z} = \mathbf{WX}\boldsymbol{\theta} + \mathbf{X}\boldsymbol{\beta} + \mathbf{e}.$$

The partial effect of a regressor k is given by

$$\frac{\partial \mathbf{z}}{\partial \mathbf{x}_k} = \mathbf{I}\beta_k + \mathbf{W}\theta_k.$$

We usually associate parameters with the **average partial effect (APE)**,^a and can interpret β_k as the *direct APE*, and can fix $\boldsymbol{\theta}$ at the *indirect APE* by setting $\mathbf{W}$ such that $\sum_i \sum_j w_{ij} = N$.

^aAn alternative, when some agents are not linked in the network, is the average partial effect for all linked agents.

For the full linear network model, let $\mathbf{z}$ be a latent quantity that goes the network filter.

The same reasoning holds for the autoregressive parameter λ .

The scaling factor is

$$\frac{N}{\sum_i \sum_j g_{ij}}.$$

Normalization for estimation [◀ Back](#)

Consider a **network autoregression**

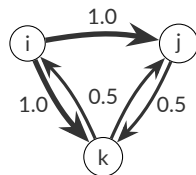
$$\mathbf{y} = (\mathbf{I} - \lambda \mathbf{W} \mathbf{y})^{-1} \mathbf{z}.$$

We need to ensure invertibility and stability.

Theorem

Let $\mathbf{I}$ denote the identity matrix, and α be a real scalar. Then $\mathbf{I} - \alpha \mathbf{A}$ is stationary for $\alpha \in (-\rho_{\mathbf{A}}, \rho_{\mathbf{A}})$, where $\rho_{\mathbf{A}}$ denotes the spectral radius of $\mathbf{A}$.

For estimation, we normalize the autoregressive term with the **inverse spectral radius**. This relates the parameter $\lambda^s \in (-1, 1)$ to the *dominant eigenvector* of the network.



Row-normalization distorts, e.g., the *eigencentality*

EC	<i>i</i>	<i>j</i>	<i>k</i>
$\mathbf{G}$	2^{-1}	6^{-1}	3^{-1}
$\tilde{\mathbf{W}}$	3^{-1}	3^{-1}	3^{-1} .

By the spectral radius being the infimum norm, λ^s is at most the average partial effect.

A Beta prior ...

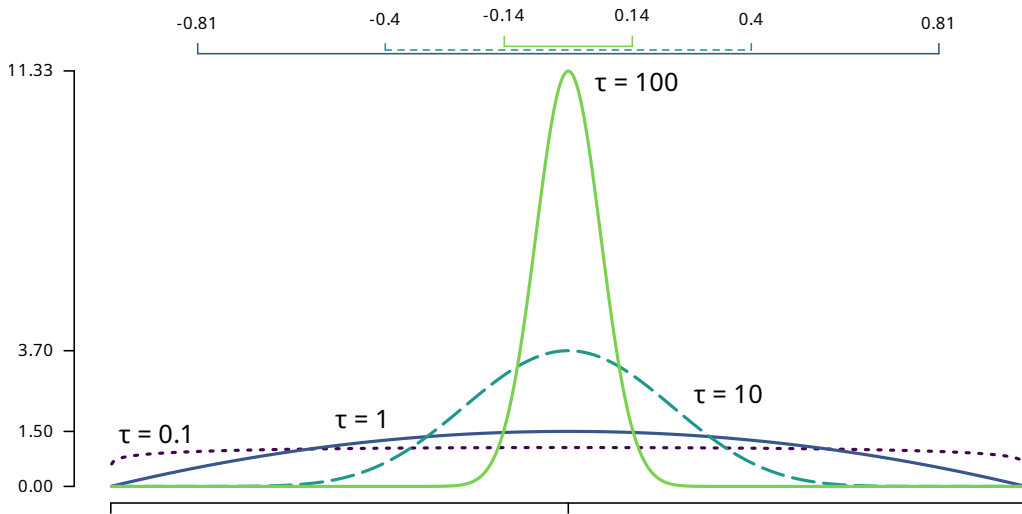


Figure 8: Scaled Beta(1 + τ , 1 + τ) densities with increasing weight, τ .

...with a Gamma mixing distribution [◀ Back](#)

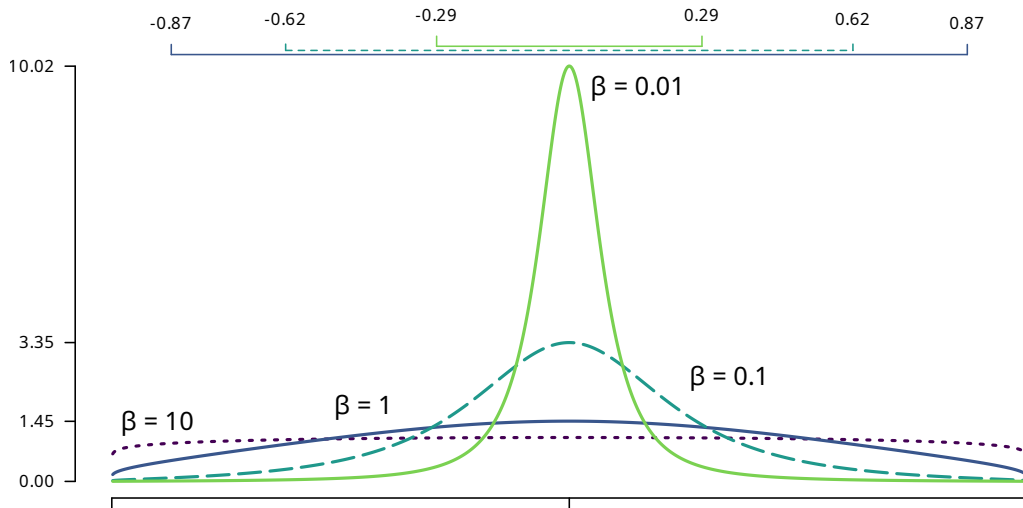


Figure 9: Scaled Beta(1 + τ , 1 + τ), $\tau \sim \text{Exp}(\beta)$ with increasing weight, $\mathbb{E}[\tau] = 1/\beta$.

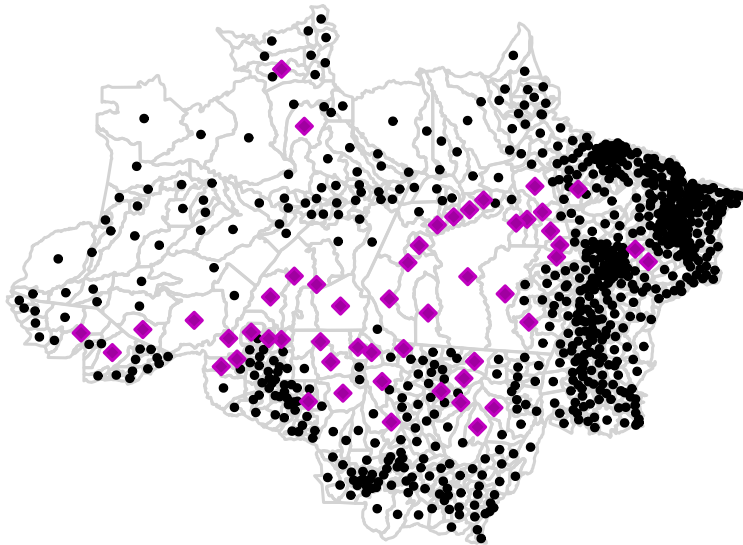


Figure 10: Centroids of the municipalities in the Legal Amazon. Priority municipalities are marked in **purple**.

■ Gibbs sampler

0. Let i be zero and set an initial value $\tilde{\beta}_i$
1. Draw σ_{i+1}^2 from $p(\sigma^2 \mid \tilde{\beta}, \cdot)$
2. Draw $\tilde{\beta}_{i+1}$ from $p(\tilde{\beta} \mid \sigma_{i+1}^2, \cdot)$
3. Increment i and go to Step 1 if more samples are desired.

■ Metropolis-Hastings step (for δ)

0. Let i be zero and set an initial value δ_i
1. Propose a value for δ^* using $Q(\delta^* \mid \delta_i)$
2. Set δ_{i+1} to δ^* with probability $\alpha(\delta^* \mid \delta_i)$
3. Increment i and go to Step 1 if more samples are desired.

The acceptance probability α is the ratio of the conditional posteriors and proposal density Q evaluated at the current and proposed values. When $\dim(\delta)$ is large, we loop over blocks of its elements to improve mixing.

In standard models, we'd compute the **spectral decomposition** of **W** **once** and compute the determinant using **W**'s eigenvalues (ω_i), as

$$\ln |\mathbf{I} - \lambda \mathbf{W}| = \sum_{i=1}^N \ln (1 - \lambda \omega_i).$$

However, our **W** is **mutable**, and computing eigenvalues for every draw of δ is prohibitive at $\mathcal{O}(N^3)$ complexity.

With limited parameters for the network structure, I propose

- the **Gaussian process approximation**

$$|\mathbf{S}(\lambda, \cdot)| \approx \text{GP}(\mu(\lambda, \cdot), \Sigma(\lambda, \cdot)),$$

- with *Arnoldi* / *Lanczos* for normalization of **W**.

Gaussian process approximation [◀ Back](#)

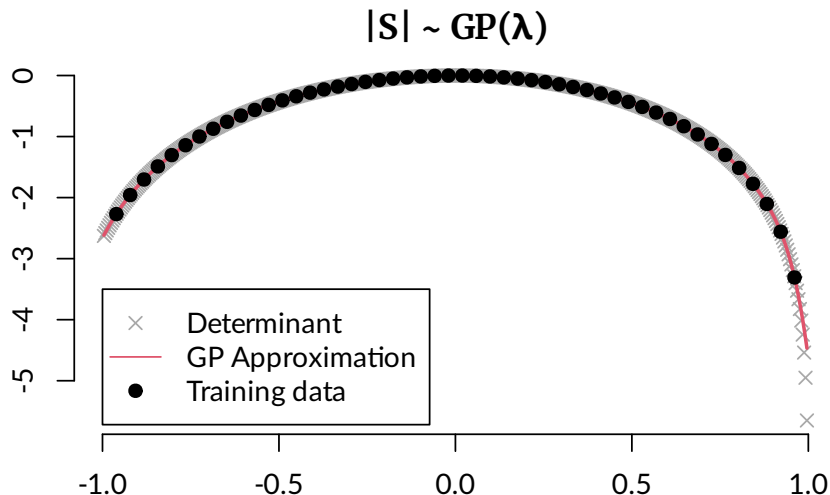


Figure 11: GP approximation to $|S(\lambda)|$ using 50 training samples. Distances are between $N = 100$ locations with Uniform random coordinates.

$|\mathbf{S}| \sim \text{GP}(\boldsymbol{\lambda}, \boldsymbol{\delta}), \text{ absolute error}$

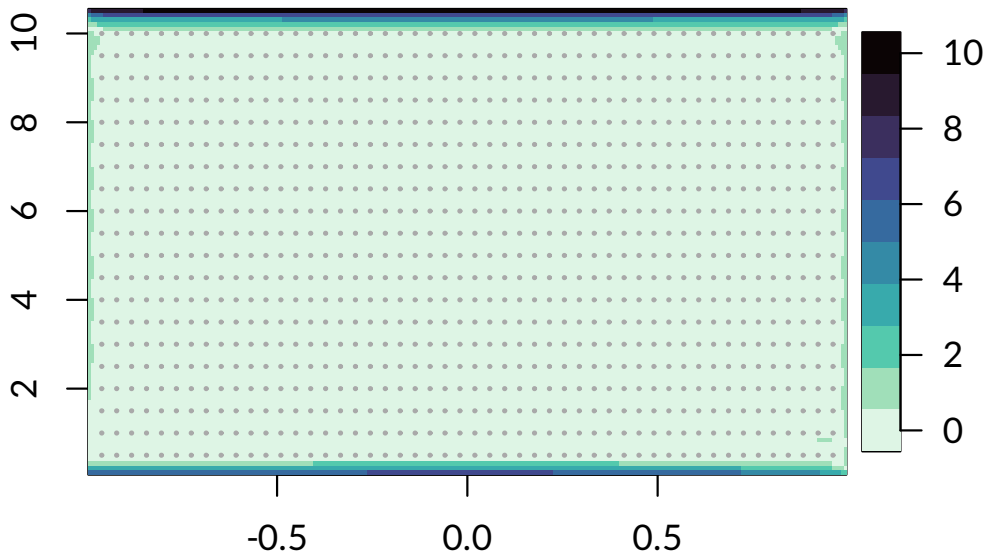
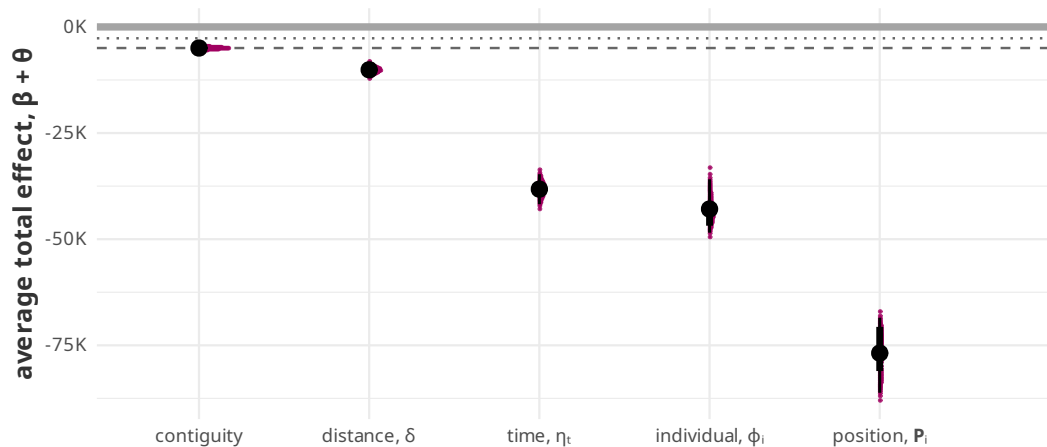
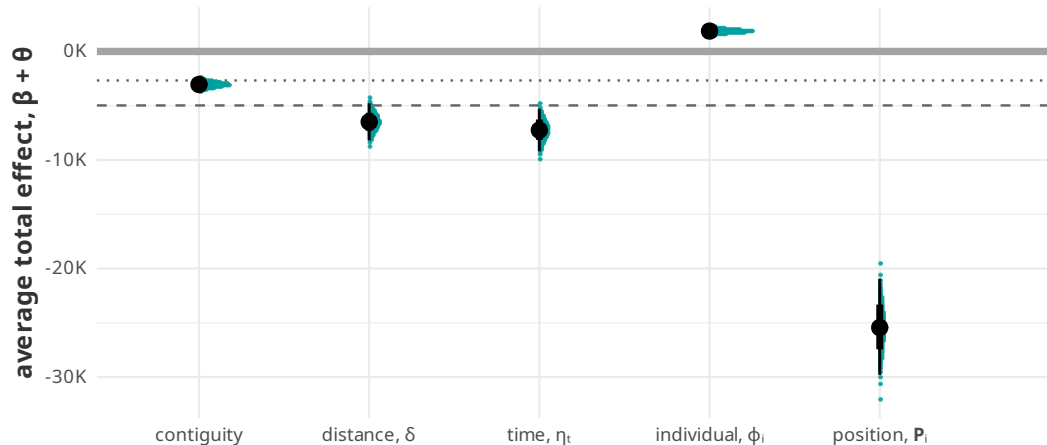


Figure 12: GP approximation to $|\mathbf{S}(\boldsymbol{\lambda}, \boldsymbol{\delta})|$ using 50×20 training samples.

Results — local spillovers

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Results — local and global spillovers

[◀ Back](#)

Outdegrees by treatment status

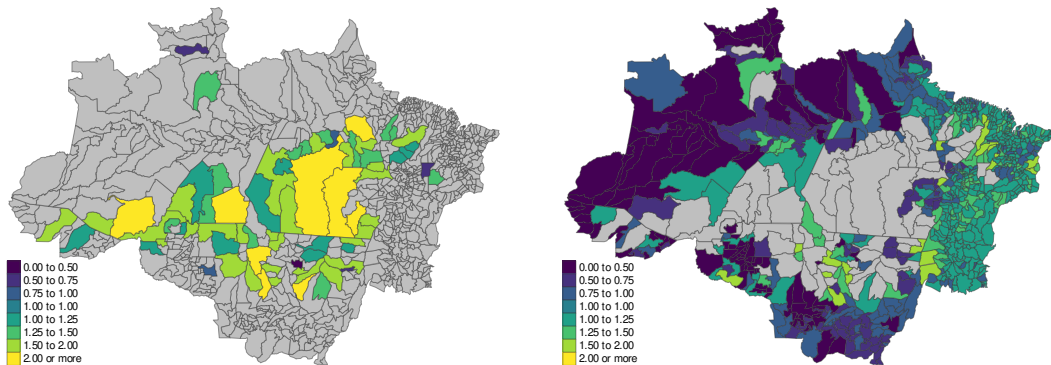
[◀ Back](#)

Figure 13: Relative outdegrees of priority (left) and other (right) municipalities as obtained from the full model, using $W(\delta, P)$.

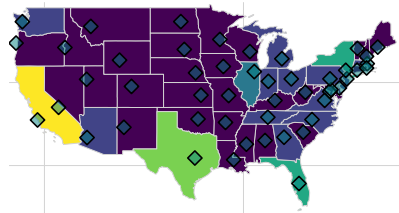
Simulation — US population

[◀ Back](#)

The network is determined as

$$g_{ij} = \exp \left\{ -\delta_i \times d \left(\mathbf{p}_i, \mathbf{p}_j \right) \right\},$$

where **popularity** δ_i depends on a state's population, and $\mathbf{p}_i$ its **population center**.



State population and its centers.

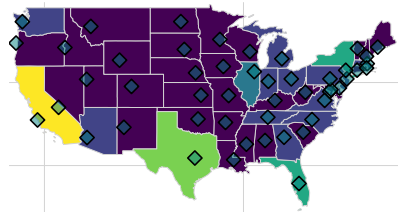
Simulation — US population

[◀ Back](#)

The network is determined as

$$g_{ij} = \exp \left\{ -\delta_i \times d(\mathbf{p}_i, \mathbf{p}_j) \right\},$$

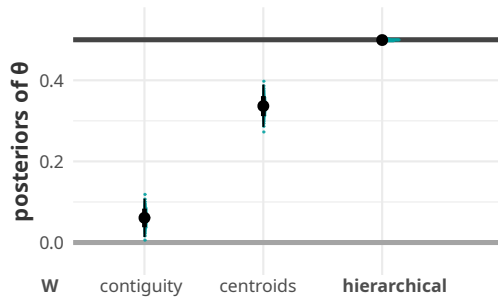
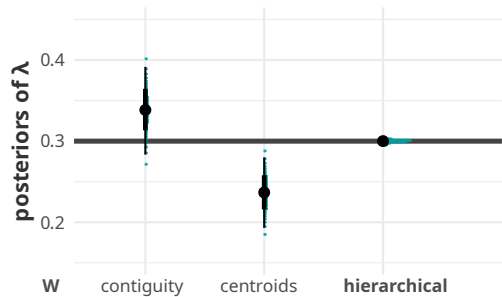
where **popularity** δ_i depends on a state's population, and $\mathbf{p}_i$ its **population center**.

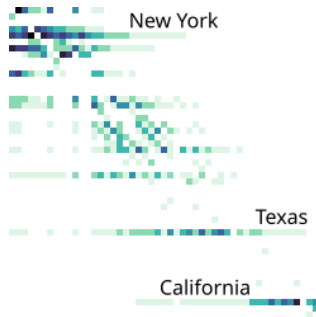
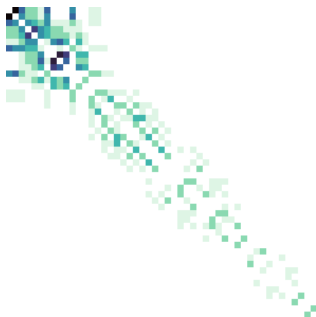
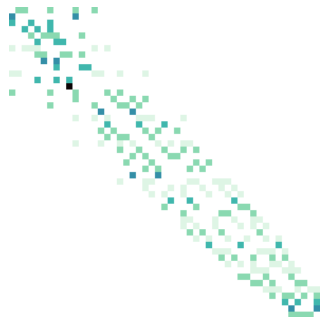
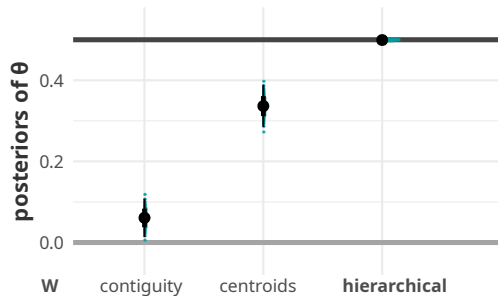
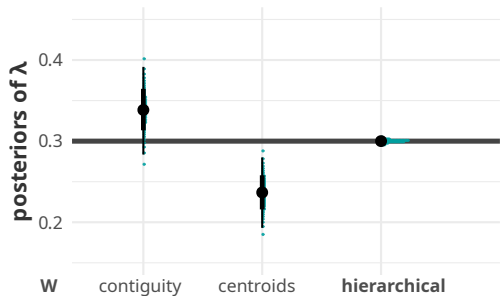


State population and its centers.

We'll start by estimating λ, θ in a long panel ($T = 50$) using

- **contiguity** between states,
- distance-decay between **centroids**, and
- the *true model* of **location & popularity**.





W based on **contiguity**, **distance-decay**, and the **true network**.

Simulation — US centroids

[◀ Back](#)

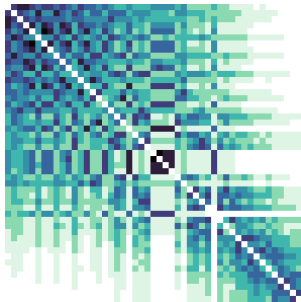
The network is determined as

$$g_{ij} = \exp \left\{ -\delta \times d \left(\mathbf{p}_i, \mathbf{p}_j \right) \right\},$$

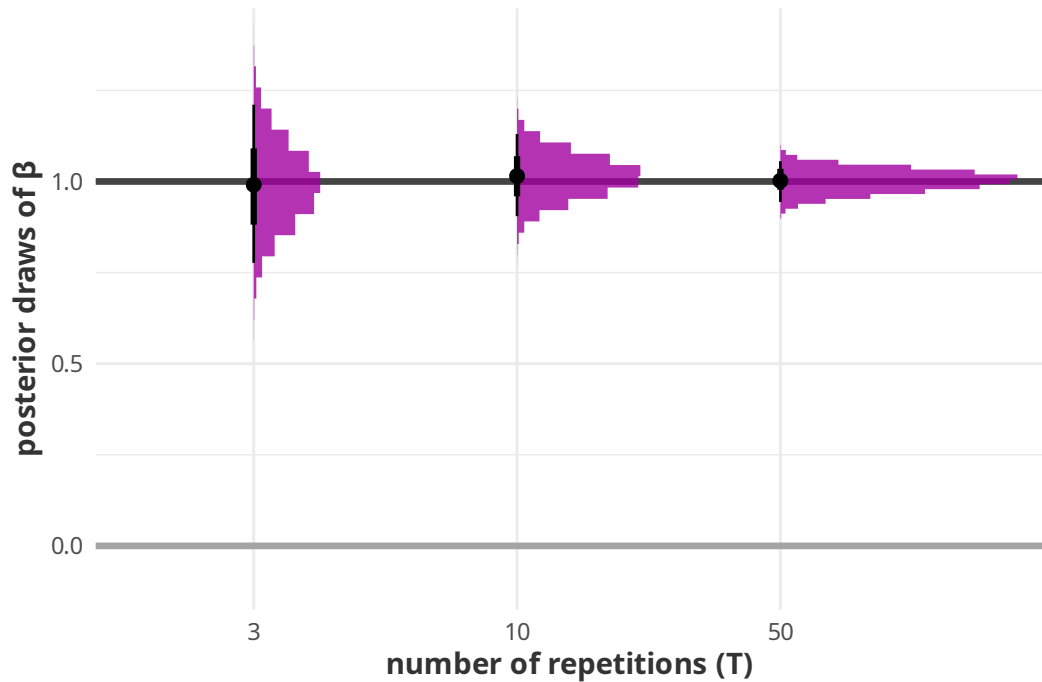
where $\mathbf{p}_i$ are **centroids**, and

- the network is rather **dense**,
- I initialize the sampler at **random locations** to illustrate convergence.

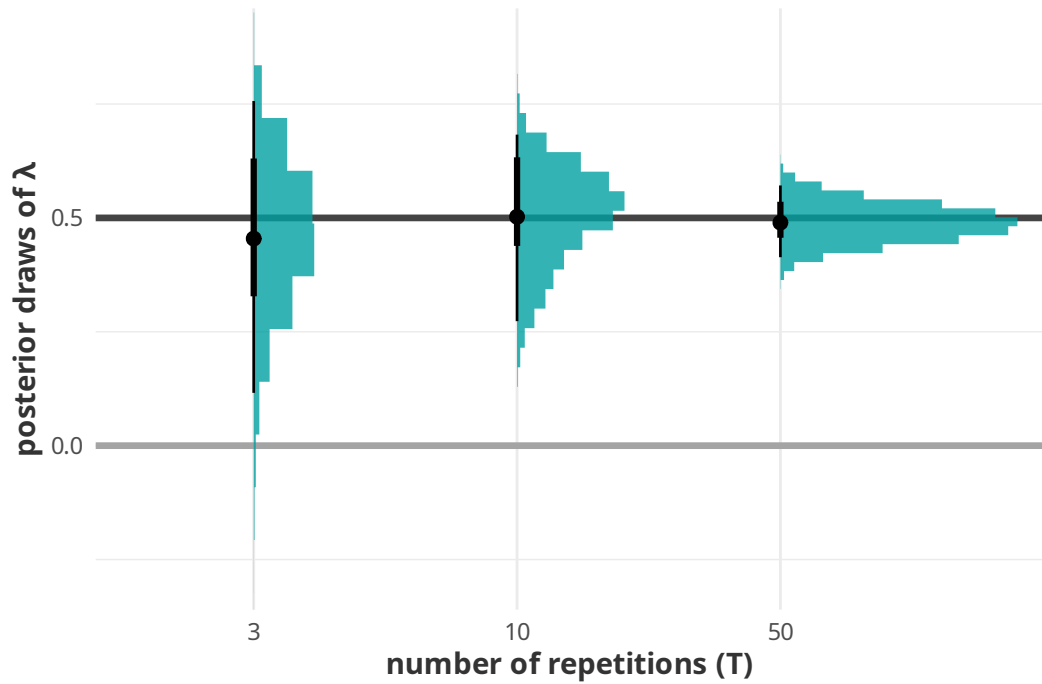
We'll have a look at **posteriors of λ** for multiple simulations after a **short burn-in** of 1,000 draws.



Coefficient β (N = 49)



Connectivity strength λ (N = 49)



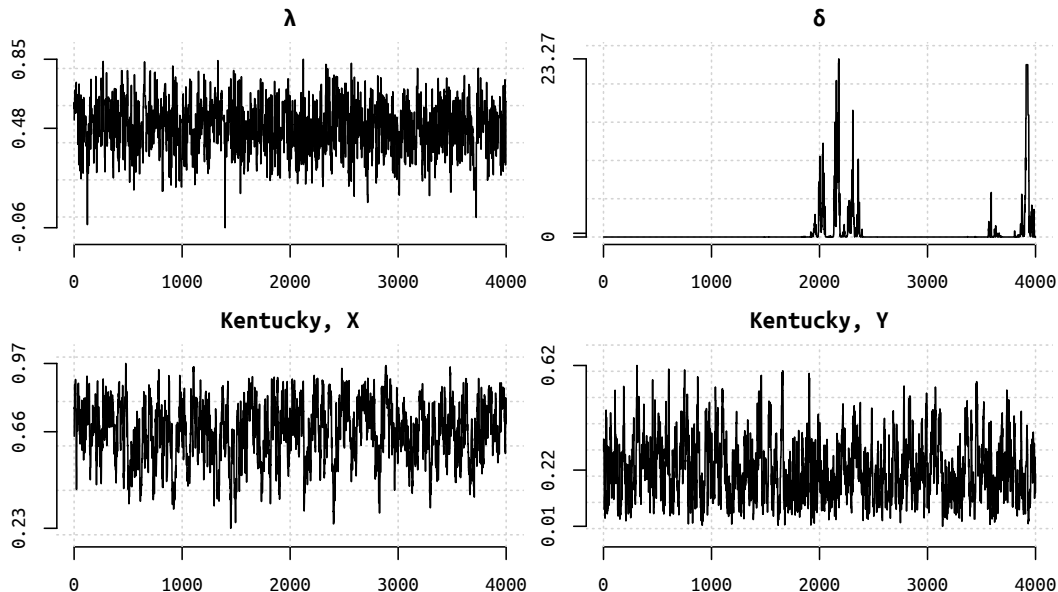


Figure 14: Traceplots for the posterior draws of λ , δ (note the poor mixing), and the (scaled) coordinates of Kentucky based on $T = 3$ network observations.

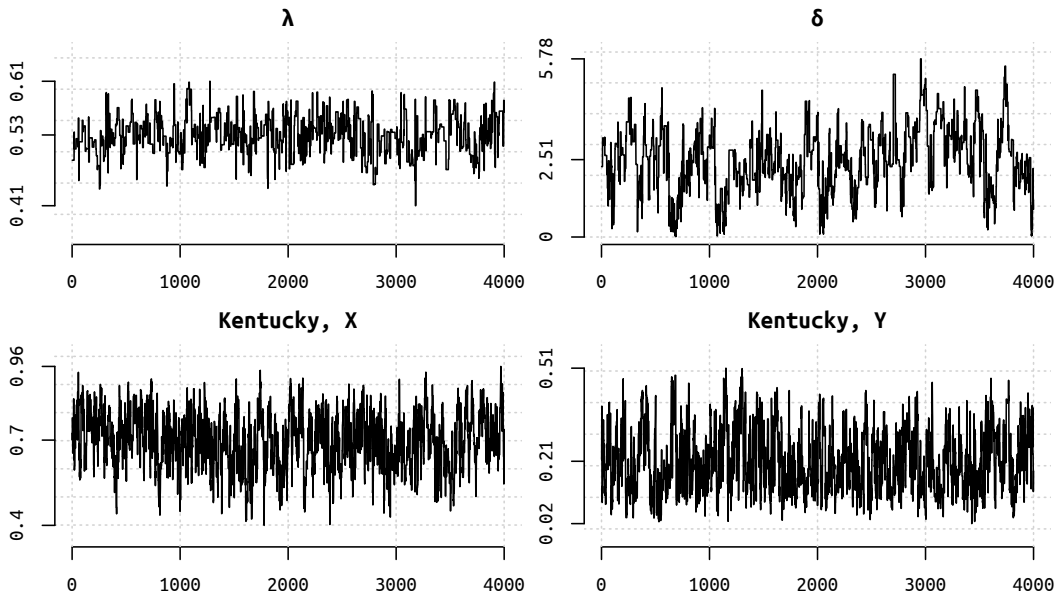


Figure 15: Traceplots for the posterior draws based on $T = 50$ network observations. Note the improved mixing behavior of δ . [◀ Back](#)

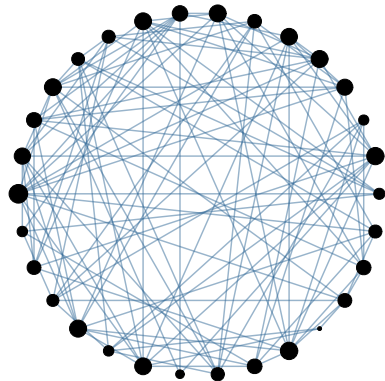
Simulation — the Erdős–Rényi graph [◀ Back](#)

The graph ($N \in \{30, 50\}$) is determined as

$$g_{ij} = \begin{cases} 1 & \text{with probability 0.25,} \\ 0 & \text{otherwise.} \end{cases}$$

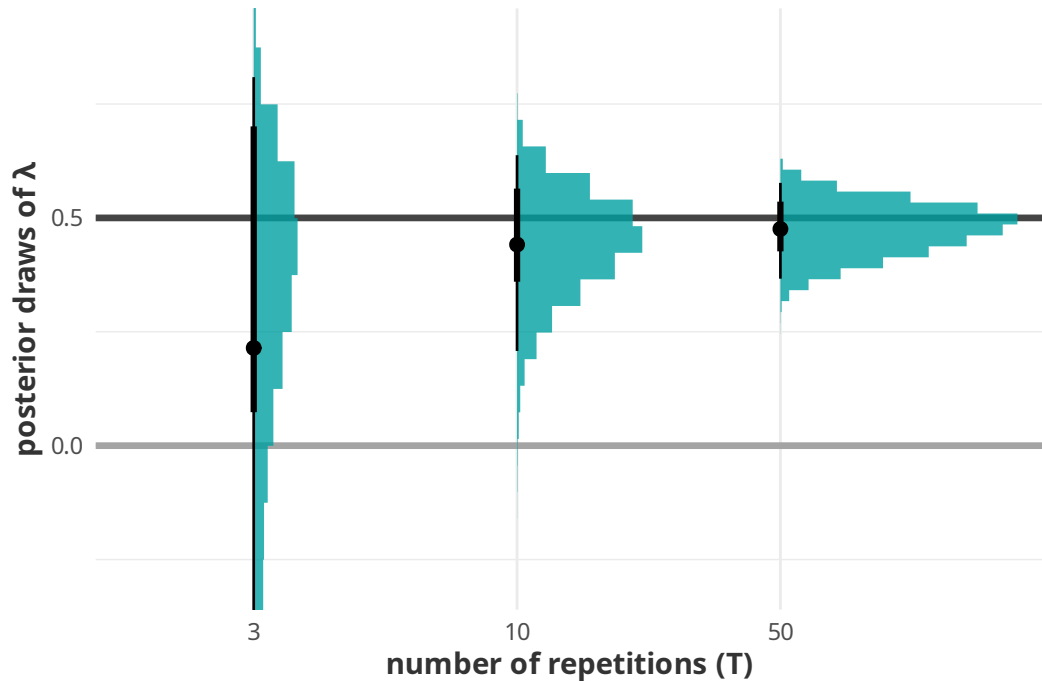
Our model uses the same **distance-decay** specification as before, but no true embedding exists.

To **highlight convergence**, we'll have a look at *posteriors of λ* for multiple simulations after a **short burn-in** of 1,000 draws.



A realization of $\mathcal{G}(30, 0.25)$.

Connectivity strength λ (N = 30)



Connectivity strength λ (N = 50)

